

Multi-Axis Controller V25



GESSMANN®

The V25 is a compact and robust joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V25 series is hugely customisable.

Technical data

Mechanical life V25	8 million operating cycles
Supply voltage	See interface
Operation temperature	-40°C to +85°C
Degree of protection	Up to IP67
Functional safety	PLd compatible (EN ISO 13849, complies SIL2 to DIN EN IEC 61508)



	V25	S8	P	Example T	-Z	-B10	-E...	-S...	-X
Basic unit									
V25.1 Multi-Axis Controller, 1-axis									
V25 Multi-Axis Controller, 2-axis									
Control-handle long									
Standard 100 mm*									
S8 +20 mm									
*Only available in combination with a handle!									
Gate									
P Cross gate (deflection angle max. 15°)									
Grip / Palm Grip									
Knob (included in basic unit!)									
M Mechanical zero interlock									
T Knob with dead man									
H Knob with signal button									
D Knob with push button KDA/70									
B ... Palm Grip B... (see page palm grip 163)									
Spring return (Included in basic unit!)									
Z Spring return									
Degree of protection									
B Cover housing (included in basic unit!)									
B10 Joystick-main board sealed (IP67)*1									
B11 Joystick-main board sealed (IP67) and grip function sealed, grip with drain hole*1									
For a schematic description of the protection class (see page 128)									
*1 not for interface E321x, E421x, E6xx, E7xx possible!									
Interface (description see on the following page)									
E0xx Switching output									
E1xx Voltage output									
E2xx Current output									
E3xx CAN-interface									
E4xx CAN Safety interface									
E6xx Profinet									
E7xx PROFIsafe									
E9xx Other outputs									

Technical details may vary based on configuration or application! Technical data subject to change without notice!

V25 S8 P T -Z -B10 -E... -S... -X

Plug connectors

S... Standard plug connectors (see page 127)

Special model

X Special / customer specified

Combination possibilities with our grips

B1  p. 211	B2  p. 209	B3  p. 206	B5  p. 204	B6  p. 202	B7 B8  p. 200	B9  p. 198	B10  p. 196	B14 B15  p. 194
 p. 192	 p. 190	 p. 188	 p. 186	 p. 183	 p. 181	 p. 179	 p. 177	 p. 175
 p. 173	 p. 171	 p. 169	 p. 167	 p. 165	 p. 163			

Digital output

Supply voltage	9-32 V DC	
Current carrying capacity	Direction signal 150 mA Zero position signal 500 mA	
Mounting depth A	60 mm	
Wiring	1. cable 14 x 0,25 mm ² 500 mm long without plug connector 2. cable 14 x 0,25 mm ² (optional for grip function) 500 mm long without plug connector Optional with plug connector (standard plug connectors see page 127)	S
2 Direction signals + 1 zero position signal (galvanically isolated) per axis		
	1 axis	E001 1
	2 axis	2

Voltage output (not stabilized)

Supply voltage	4,75-5,25 V DC	
Current carrying capacity	Direction signal 8 mA	
Mounting depth A	60 mm	
Wiring	1. cable 14 x 0,25 mm ² 500 mm long without plug connector 2. cable 14 x 0,25 mm ² (optional for grip function) 500 mm long without plug connector Optional with plug connector (standard plug connectors see page 127)	S
0,5...2,5...4,5 V redundant + 2 direction signals per axis		
	1 axis	E104 1
	2 axis	2
	Output options	
	Characteristic:	
	Inverse dual	1
	Dual	2
	Inverse Dual with dead zone +/- 3° (standard)	3
	Dual with dead zone +/- 3°	4

Voltage output			
Supply voltage	9-32 V DC (*11,5-32)		S
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
Mounting depth A	60 mm		
Wiring	1. cable 14 x 0,25 mm ² 500 mm long without plug connector		
	2. cable 14 x 0,25 mm ² (optional for grip function) 500 mm long without plug connector		
	Optional with plug connector (<i>standard plug connectors see page 127</i>)		
0,5...2,5...4,5 V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis			
	1 axis	E112 1	
	2 axis	2	
	3 axis*	3	
	4 axis*	4	
0...5...10 V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, supply voltage 11,5 - 32 V DC			
	1 axis	E132 1	
	2 axis	2	
	3 axis*	3	
	4 axis*	4	
10...0...10 V + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, supply voltage 11,5 - 32 V DC, sensor redundant with error monitoring and error signal			
	1 axis	E136 1	
	2 axis	2	
	3 axis*	3	
	4 axis*	4	
Output options			
Characteristic:			
	Inverse dual * ¹	1	
	Dual * ¹	2	
	Inverse dual with dead zone +/- 3° * ¹ (standard)	3	
	Dual with dead zone +/- 3° * ¹	4	
* ¹ Not combinable with output E136X			
	Single * ²	5	
	Single with dead zone +/- 3° * ² (standard)	6	
* ² Not combinable with output E112X and E132X			
Digital output signals:			
Output signals standard:			
	Direction signals and zero position signals 1,5A 24 V DC		1
*Axis for grip functions, interface can vary depending upon actuation element!			
Voltage output with other value on request!			

Current output				
Supply voltage	9-32 V DC			
Current carrying capacity	Direction signal 150 mA			
	Zero position signal 500 mA			
Mounting depth A	60 mm			
Wiring	1. cable 14 x 0,25 mm ² 500 mm long without plug connector			
	2. cable 14 x 0,25 mm ² (optional for grip function) 500 mm long without plug connector			
	Optional with plug connector (<i>standard plug connectors see page 127</i>)			S
0...10...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal				
	1 axis		E206 1	
	2 axis		2	
	3 axis*		3	
	4 axis*		4	
20...0...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal				
	1 axis		E208 1	
	2 axis		2	
	3 axis*		3	
	4 axis*		4	
4...12...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal				
	1 axis		E214 1	
	2 axis		2	
	3 axis*		3	
	4 axis*		4	
20...4...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal				
	1 axis		E216 1	
	2 axis		2	
	3 axis*		3	
	4 axis*		4	
Output options				
	Single			5
	Single with dead zone +/- 3° (standard)			6
Digital output signals:				
Output signals standard:				
	Direction signals and zero position signals 1,5A 24 V DC			1

**Axis for grip functions, interface can vary depending upon actuation element!*

Current output with other value on request!

Identification of the installation variants with switching directions:



CAN			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA Zero position signal 100 mA External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs) Digital switching output (potential-free) 100 mA		
Mounting depth A	60 mm (expansion stage 1) 70 mm (expansion stage 2)		
Protocol	CANopen CiA DS 301 or SAE J1939 (based on)		
Baud rate	20 kBit/s to 1 Mbit/s (standard 250 kBit/s)		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male) CAN (OUT) cable 300 mm with plug connector M12 (female) External in-/outputs cable 300 mm long without plug connector External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs) Optional with plug connector (<i>standard plug connectors see page 127</i>)		
CAN expansion stage 1			S
- 6 analog joystick axis			E320 1
- 16 digital joystick functions (of which 2 inputs can be used for the cap. sensor)			
CAN expansion stage 2			E321 1
- 12 analog joystick axis			
- 16 digital joystick functions (of which 2 inputs can be used for the cap. sensor)			
With additional external in-/outputs			
- 8 external LED-outputs (dimnable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs			2
- 16 external LED-outputs (dimnable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs			3
- 24 external LED-outputs (dimnable), 1 switching output (potential-free, 100 mA), 24 external digital inputs			4
- 32 external LED-outputs (dimnable), 1 switching output (potential-free, 100 mA), 32 external digital inputs			5
*External LED-outputs can be used for LEDs in the grip (Control of intelligent RGB LEDs possible on request)			
Main-axis with additional digital outputs separately wired (not via CAN)			
- 2 direction signals per main axis + 1 zero position signal (potential-free) per main axis			3

CAN Safety			
Supply voltage	9-32 V DC		
Idle current consumption	120 mA (24 V DC)		
Current carrying capacity	Direction signal 100 mA		
	Zero position signal 100 mA (potential-free)		
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)		
	Digital switching output (potential-free) 100 mA		
Baud rate	20 kBit/s to 1 MBit/s (standard 250 kBit/s)		
Mounting depth	60 mm (expansion stage 1)		
	70 mm (expansion stage 2)		
Protocol	CANopen Safety EN50325-5 or J1939-76		
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)		
	CAN (OUT) cable 300 mm with plug connector M12 (female)		
	External in-/outputs cable 300 mm long without plug connector		
	External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs)		
	Optional with plug connector (standard plug connectors see page 127)		
CAN Safety expansion stage 1		420 1	S
- 6 analog joystick axis - 16 digital joystick functions (of which 2 inputs can be used for the cap. sensor) (Control of intelligent RGB LEDs possible on request)			
CAN Safety expansion stage 2		E421 1	
- 12 analog joystick axis - 16 digital joystick functions (of which 2 inputs can be used for the cap. sensor)			
With additional external in-/outputs			
- 8 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs		2	
- 16 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs		3	
- 24 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 24 external digital inputs		4	
- 32 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 32* external digital inputs		5	
*External LED-outputs can be used for LEDs in the grip!			
(Control of intelligent RGB LEDs possible on request)			
Main-axis with additional digital outputs separately wired (not via CAN)			3
- 2 direction signals per main axis			

Profinet			
Supply voltage	18-30 V DC		
Baud rate	To 100 MBit/s		
Output value	0...512...1023		
Mounting depth A	90 mm		
Verdrahtung	Profinet (1), cable 300 mm with M12 plug connector (female)		
	Profinet (2), cable 300 mm with M12 plug connector (female)		
	Supply voltage (if applicable contact wiring) cable 12 x 0,25 mm² 300 mm long without plug connector		
	External in-/outputs, cable 300 mm long without plug connector		
Optional with plug connector (<i>standard plug connectors see page 127</i>)			S
Profinet		E602 1	
- 4 analog joystick axis			
- 20 digital joystick functions			
- Input for capacitive sensor			
With additional external in-/outputs			
- 8 external LED-outputs, 8 external digital inputs		2	
<i>*External LED-outputs can be used in the grip for LEDs</i>			
Main-axis with additional signals separately wired (not via profinet)			
- 2 direction signals + zero position signal (potential-free) per main-axis			3

PROFIsafe

Supply voltage	18-30 V DC
Baud rate	To 12 MBit/s
Output value	0...512...1023
Mounting depth A	90 mm
Wiring	Profinet (1), cable 300 mm with M12 plug connector (female)
	Profinet (2), cable 300 mm with M12 plug connector (female)
	Supply voltage (if applicable contact wiring) cable 12 x 0,25 mm ² 300 mm long without plug connector
	External in-/outputs, cable 300 mm long without plug connector
	Optional with plug connector (<i>standard plug connectors see page 127</i>)

S

PROFIsafe

- 4 analog joystick axis
- 20 digital joystick functions
- Input for capacitive sensor

With additional external in-/outputs

- 8 external LED-outputs, 8 external digital inputs

**External LED-outputs can be used in the grip for LEDs*

E702 1

2

Main-axis with additional signals separately wired (not via profinet safe)

- 2 direction signals + zero position signal (potential-free) per main-axis

3

Other outputs

Voltage output for PVG32 0,25...0,5...0,75Us, power supply 9-32 V DC

Option Input for capacitive sensor

Mounting depth A 60 mm

- Wiring:
1. cable 14 x 0,25 mm² 300 mm long without plug connector
 2. cable 14 x 0,25 mm² 300 mm long without plug connector (optional for grip function)

Optional with plug connector (*standard plug connectors see page 127*)

S

1 axis

E907 1

2 axis

2

3 axis

3

4 axis

4

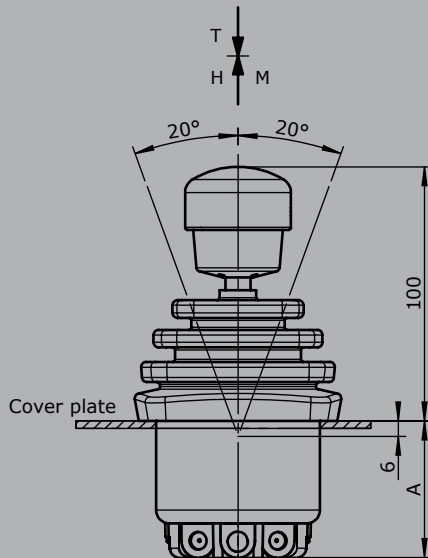
Main-axis with additional direction signals and zero direction signals (potential-free) per main-axis

3

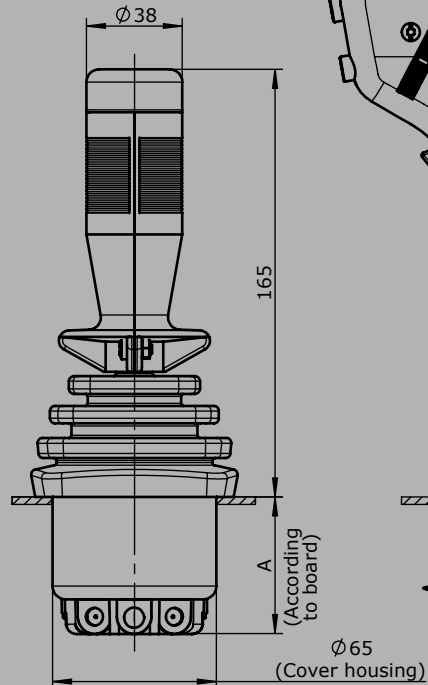
Attachments

Z01 Mating connector M12 male insert with 2 m cable	20201140
Z02 Mating connector M12 female insert with 2 m cable	20202298

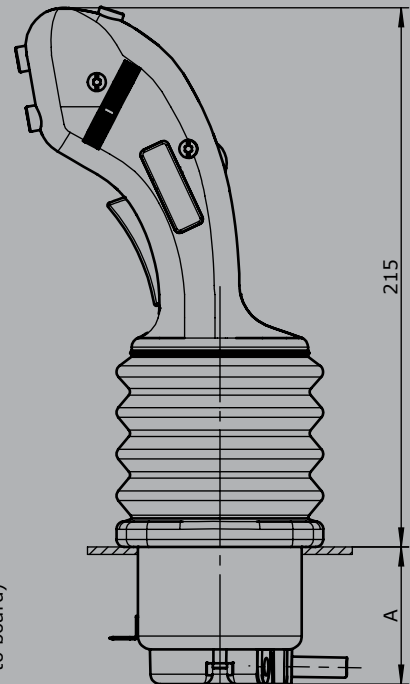
T = Dead man's button
H = Signal button
M = Latch for mechanical
zero interlock



Palm grip B1



Palm grip B3



Palm grip B25

