

# Multi-Axis Controller V25



The V25 is a compact and robust joystick commonly used in electro-hydraulic applications. Long life and high reliability is ensured by the latest contactless hall-technology. With many outputs and grip options the V25 series is hugely customisable.

## Technical data

Mechanical life V25	8 million operating cycles
Supply voltage	See interface
Operation temperature	-40°C to +85°C
Degree of protection	up to IP67
Functional safety	PLd compatible (EN ISO 13849, complies SIL2 to DIN EN IEC 61508)



	V25	S8	P	Example T	-Z	-B10	-E...	-S...	-X
<b>Basic unit</b>									
V25.1	1-axis								
V25	2-axis								
<b>Control-handle long</b>									
	Standard 100 mm*								
S8	+20 mm								
*Only available in combination with a handle!									
<b>Gate</b>									
P	Cross gate (deflection angle max. 15°)								
<b>Grip / Palm Grip</b>									
	Knob (included in basic unit!)								
M	Mechanical zero interlock								
T	Knob with dead man								
H	Knob with signal button								
D	Knob with push button KDA/70								
B ...	Palm Grip B... (see page Palm Grip 154)								
<b>Spring return (included in basic unit!)</b>									
Z	Spring return								
<b>Degree of protection</b>									
B	Cover housing								
B10	Joystick-main board sealed								
B11	Joystick-main board sealed and grip function sealed, grip with drain hole								
For a schematic description of the protection class, see page 121									
<b>Interface (description see on the following page)</b>									
E0xx	Switching output								
E1xx	Voltage output								
E2xx	Current output								
E3xx	CAN-interface								
E4xx	CANopen Safety interface								
E9xx	Other outputs								

Technical details may vary based on configuration or application! Technical data subject to change without notice!

V25 S8 P T -Z -B10 -E... -S... -X

### Plug connectors

S... Standard plug connectors (see page 120)

### Special model

X Special / customer specified

### Combination possibilities with our grips



### Digital output

Supply voltage	9-32 V DC	
Current carrying capacity	Direction signal 150 mA Zero position signal 500 mA	
Mounting depth A	60 mm	
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without plug connector 2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip function) 500 mm long without plug connector Optional with plug connector (standard plug connectors see page 120)	S
2 Direction signals + 1 zero position signal (galvanically isolated) per axis		
	1 axis	E001 1
	2 axis	2

### Voltage output (not stabilized)

Supply voltage	4,75-5,25 V DC	
Current carrying capacity	Direction signal 8 mA	
Mounting depth A	60 mm	
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without plug connector 2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip function) 500 mm long without plug connector Optional with plug connector (standard plug connectors see page 120)	S
0,5...2,5...4,5 V redundant + 2 direction signals per axis		
	1 axis	E104 1
	2 axis	2
<b>Output options</b>		
Characteristic:		
Inverse dual		1
Dual		2
Inverse Dual with dead zone +/- 3° (standard)		3
Dual with dead zone +/- 3°		4

Technical details may vary based on configuration or application! Technical data subject to change without notice!

Voltage output	
Supply voltage	9-32 V DC (*11,5-32)
Current carrying capacity	Direction signal 150 mA
	Zero position signal 500 mA
Mounting depth A	60 mm
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without plug connector
	2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip function) 500 mm long without plug connector
	Optional with plug connector ( <i>standard plug connectors see page 120</i> )
S	
0,5...2,5...4,5 V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis	
	1 axis E112 1
	2 axis 2
	3 axis* 3
	4 axis* 4
0...5...10 V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, supply voltage 11,5 - 32 V DC	
	1 axis E132 1
	2 axis 2
	3 axis* 3
	4 axis* 4
10...0...10 V + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, supply voltage 11,5 - 32 V DC, sensor redundant with error monitoring and error signal	
	1 axis E136 1
	2 axis 2
	3 axis* 3
	4 axis* 4
<b>Output options</b>	
Characteristic:	
Inverse dual *1	1
Dual *1	2
Inverse dual with dead zone +/- 3° *1 (standard)	3
Dual with dead zone +/- 3° *1	4
*1 not combinable with output E136X	
Single *2	5
Single with dead zone +/- 3° *2 (standard)	6
*2 not combinable with output E112X and E132X	
Digital output signals:	
Output signals standard:	
Direction signals and zero position signals 1,5A 24 V DC	1
*Axis for grip functions, interface can vary depending upon actuation element!	
Voltage output with other value on request!	

### Current output

Supply voltage	9-32 V DC		
Current carrying capacity	Direction signal 150 mA		
	Zero position signal 500 mA		
Mounting depth A	60 mm		
Wiring	1. cable 14 x 0,25 mm <sup>2</sup> 500 mm long without plug connector		
	2. cable 14 x 0,25 mm <sup>2</sup> (optional for grip function) 500 mm long without plug connector		
	Optional with plug connector ( <i>standard plug connectors see page 120</i> )		S
0...10...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal			
	1 axis	E206	1
	2 axis		2
	3 axis*		3
	4 axis*		4
20...0...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal			
	1 axis	E208	1
	2 axis		2
	3 axis*		3
	4 axis*		4
4...12...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal			
	1 axis	E214	1
	2 axis		2
	3 axis*		3
	4 axis*		4
20...4...20 mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal			
	1 axis	E216	1
	2 axis		2
	3 axis*		3
	4 axis*		4
	<b>Output options</b>		
	Single		5
	Single with dead zone +/- 3° (standard)		6
	Digital output signals:		
	Output signals standard:		
	Direction signals and zero position signals 1,5A 24 V DC		1

\*Axis for grip functions, interface can vary depending upon actuation element!

Current output with other value on request!

**Identification of the installation variants with switching directions:**



CAN	
Supply voltage	9-32 V DC
Idle current consumption	120 mA (24 V DC)
Current carrying capacity	Direction signal 100 mA Zero position signal 100 mA External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs) Digital switching output (potential-free) 100 mA
Mounting depth A	60 mm (expansion stage 1) 70 mm (expansion stage 2) 90 mm (expansion stage 3)
Protocol	CANopen CiA DS 301 or SAE J1939 (based on)
Baud rate	20 kBit/s to 1 Mbit/s (standard 250 kBit/s)
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male) CAN (OUT) cable 300 mm with plug connector M12 (female) External in-/outputs cable 300 mm long without plug connector External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs) Optional with plug connector ( <i>standard plug connectors see page 120</i> )
<b>CAN expansion stage 1</b>	E304 1
- 4 analog joystick axis	
- 15 digital joystick functions	
- Input for capacitive sensor	
Main-axis with additional digital outputs separately wired (not via CAN)	
- 2 direction signals per main axis	1
<b>CAN expansion stage 2</b>	E305 1
- 7 analog joystick axis	
- 15 digital joystick functions	
- 2 inputs for capacitive sensors	
With additional external in-/outputs	
- 8 external LED-outputs (dimnable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs	2
- 16 external LED-outputs (dimnable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs	3
*External LED-outputs can be used for LEDs in the grip	

<b>CAN expansion stage 3</b>		E306 1
<ul style="list-style-type: none"> <li>- 10 analog joystick axis</li> <li>- 15 digital joystick functions</li> <li>- 2 inputs for capacitive sensors</li> </ul>		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 8 external digital inputs		2
- 16 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 16 external digital inputs		3
- 24 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 24 external digital inputs		4
- 32 external LED-outputs (dimmable optional), 2 switching outputs (potential-free, 100 mA), 32 external digital inputs		5
*External LED-outputs can be used for LEDs in the grip		
<b>Main-axis with additional digital outputs separately wired (not via CAN)</b>		
- 2 direction signals + 1 zero position signal (potential-free) per axis		3
With additional analog outputs on request!		

<b>CANopen Safety</b>		
Supply voltage	9-32 V DC	
Idle current consumption	120 mA (24 V DC)	
Current carrying capacity	Direction signal 100 mA	
	Zero position signal 100 mA (potential-free)	
	External digital output for LEDs 5 mA - 30 mA (dependent on the number of LEDs)	
	Digital switching output (potential-free) 100 mA	
Baud rate	20 kBit/s to 1 MBit/s (standard 250 kBit/s)	
Mounting depth	60 mm (expansion stage 1)	
	70 mm (expansion stage 2)	
	90 mm (expansion stage 3)	
Protocol	CANopen Safety EN50325-5	
Wiring	CAN (IN) cable 300 mm with plug connector M12 (male)	
	CAN (OUT) cable 300 mm with plug connector M12 (female)	
	External in-/outputs cable 300 mm long without plug connector	
	External in-/outputs cable 300 mm long without plug connector (additional from 32 in-/outputs)	
	Optional with plug connector (standard plug connectors see page 120)	S

<b>CANopen Safety expansion stage 1</b>		E404 1
<ul style="list-style-type: none"> <li>- 4 analog joystick axis</li> <li>- 15 digital joystick functions</li> <li>- Input for capacitive sensor</li> </ul>		
<b>Main-axis with additional digital outputs separately wired (not via CAN)</b>		
- 2 direction signals per main axis		1

<b>CANopen Safety expansion stage 2</b>		E405 1
<ul style="list-style-type: none"> <li>- 7 analog joystick axis</li> <li>- 15 digital joystick functions</li> <li>- 2 inputs for capacitive sensors</li> </ul>		
With additional external in-/outputs		
- 8 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 8 external digital inputs		2
- 16 external LED-outputs (dimmable optional), 1 switching output (potential-free, 100 mA), 16 external digital inputs		3
*External LED-outputs can be used for LEDs in the grip		

## CANopen Safety expansion stage 3

- 10 analog joystick axis
- 15 digital joystick functions
- 2 inputs for capacitive sensor

E406 1

With additional external in-/outputs

- 8 external LED-outputs (dimnable optional), 2 switching outputs (potential-free, 100 mA), 8 external digital inputs
- 16 external LED-outputs (dimnable optional), 2 switching outputs (potential-free, 100 mA), 16 external digital inputs
- 24 external LED-outputs (dimnable optional), 2 switching outputs (potential-free, 100 mA), 24 external digital inputs
- 32 external LED-outputs (dimnable optional), 2 switching outputs (potential-free, 100 mA), 32 external digital inputs

2  
3  
4  
5

*\*External LED-outputs can be used for LEDs in the grip*

Main-axis with additional digital outputs separately wired (not via CAN)

- 2 direction signals + 1 zero position signal (potential-free) per axis

3

*With additional analog outputs on request!*

## Other outputs

Voltage output for PVG32 0,25...0,5...0,75Us, power supply 9-32 V DC

Option Input for capacitive sensor

Mounting depth A 60 mm

- Wiring:
1. cable 14 x 0,25 mm<sup>2</sup> 300 mm long without plug connector
  2. cable 14 x 0,25 mm<sup>2</sup> 300 mm long without plug connector (optional for grip function)

Optional with plug connector (*standard plug connectors see page 120*)

S

1 axis	E907 1
2 axis	2
3 axis	3
4 axis	4

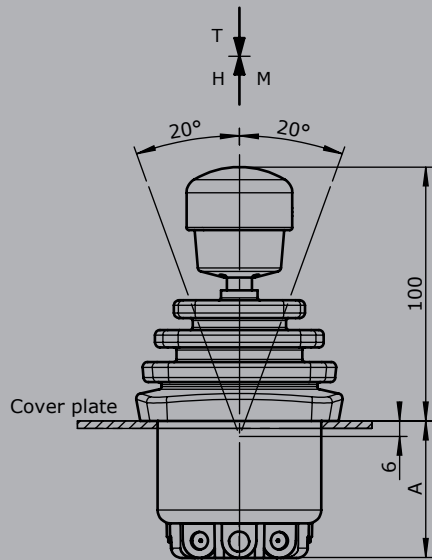
Main-axis with additional direction signals and zero direction signals (potential-free) per main-axis

3

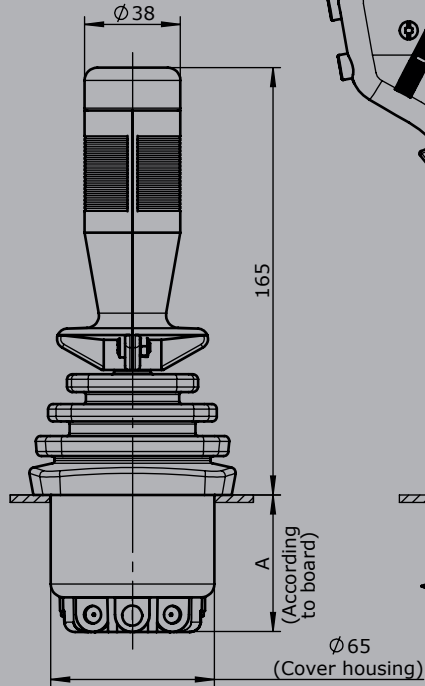
## Attachments

Z01 Mating connector M12 male insert with 2 m cable	20201140
Z02 Mating connector M12 female insert with 2 m cable	20202298

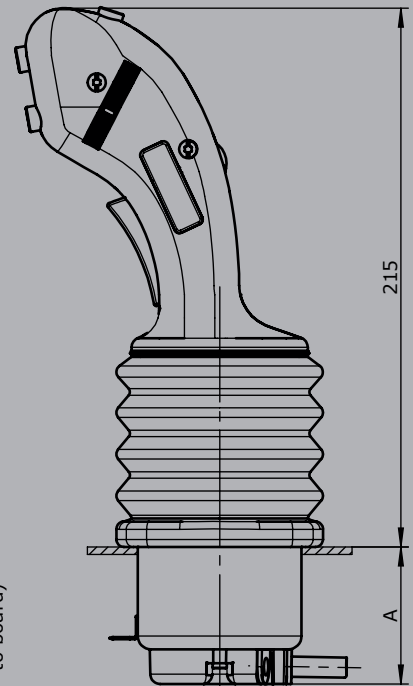
T = Dead man's button  
H = Signal button  
M = Latch for mechanical zero interlock



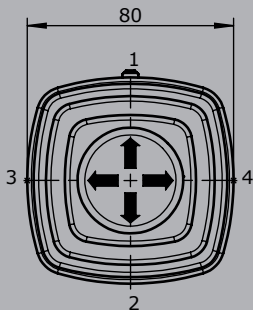
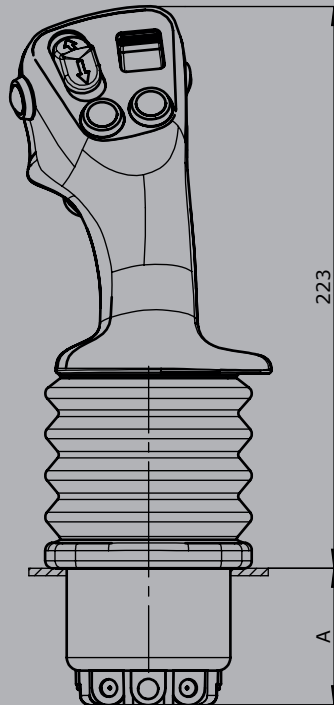
Palm grip B1



Palm grip B3



Palm grip B25



Hole pattern

